

UM Experiments

Contents

6. UM EXPERIMENTS MODULE	6-3
6.1. INTRODUCTION	6-3
6.2. OVERVIEW	6-4
6.3. REMARKS	6-6
6.4. DESCRIBING A NEW SCANNING PROJECT	6-9
6.5. ALTERNATIVES	6-9
6.5.1. Hierarchy of parameters	6-10
6.5.2. Tree of alternatives	6-11
6.5.3. Identifiers	6-11
6.5.4. Initial conditions	6-11
6.5.5. Finish conditions	6-11
6.5.6. Variables	6-13
6.5.7. Integrator	6-13
6.6. RUNNING	6-13
6.7. RESULTS	6-14
6.7.1. Wizard of graphs	6-15
6.7.2. Wizard of surfaces	6-17

6. UM Experiments module

6.1. Introduction

UM Experiments module is developed to help the researcher to analyze dynamical behavior of models at various conditions automatically. Manual running a number of numerical experiments is a quite time-consuming and laborious process where researcher has to control many different parameters of a model, save outputs and change inputs for so many experiments that often leads to mistakes. UM Experiments automatize running hundreds and thousands of numerical experiments and finally implements the idea that "machines should work; people should think".

UM Experiments module is built in the **UM Simulation** program and includes the tool for describing and executing scanning projects (*scanning*) and extra service of distributed calculations that helps to use computational capacity of computers available in your local network.

UM Experiments is entirely included into **UM Simulation** program. Every module in UM software is licensed separately. To use scanning projects the **UM Experiments** module should be available. To check if you have the **UM Experiments** module run **UM Simulation** program then select **Help | About** main menu item and make sure that you have '+' sign for **UM Experiments**, see Figure 32.1. If you use a trial UM license, your UM configuration already includes **UM Experiments**. If you are a registered user you can request for a free trial 3-month license via um@universalmecanism.com.

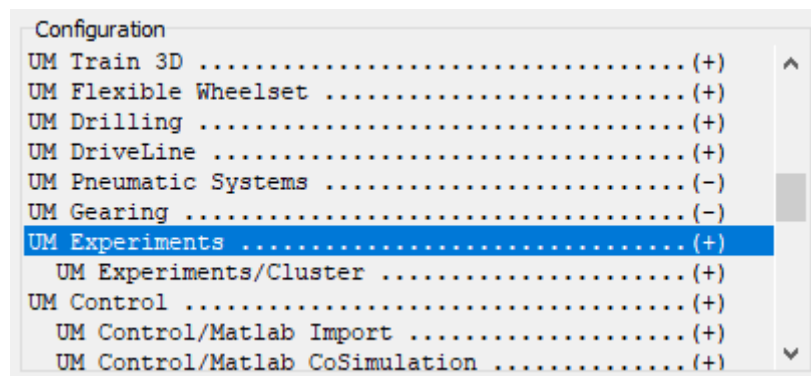


Figure 6.1. UM Experiments in the UM configuration

In the everyday engineering practice it is often required to carry out series of numerical experiments, for example to analyze dynamical behavior and sensitivity of mechanical system or to find out optimal parameters of the system. **UM Experiments** includes a set of tools (*scanning, service of distributed calculations*) for advanced analysis of dynamics of mechanical systems.

Scanning project automates fulfillment of series of numerical experiments and save results of experiments on a hard disk for posterior analysis. Thus, an engineer is released from monotonous execution of series of numerical experiments "manually" what saves working time and removes errors, which people unfortunately usually do. In other words, the researcher defines the design of experiments for scanning, and then the project is started and executed automatically. Current process statistics is available during the execution: number of executed experiments, time left. Series of numerical experiments are resistant to shut-down of power supply. In that case all re-

sults are saved on a hard disk and only results of the latter experiments that are being calculated at the time of shut-down will be lost.

There is a possibility to plot an oscillogram of any saved performance of dynamical behavior of a mechanism. Moreover, the engineer can plot so-called summary graphs and surfaces. Scanning project has no limitation in number of parameters. In other words, it is multi-parametrical. Dimensions of projects are set by the engineer so as to solve the specified problem. But on the other hand the designer has to take into account calculating efforts that are necessary for the project and find a compromise between them.

There is a special extension of the module – service of distributed calculations named **UM Cluster**. It allows using all computational powerful of a network for execution of series of numerical experiments that decreases time efforts correspondingly. This possibility is very easy and effective to use in computer centers and laboratories. Server of distributed calculations is based on using TCP/IP that allows employing for the needs of your project any computer not only in local or corporate network, but also in Internet.

6.2. Overview

Scanning of the design space is the most simple and reliable method to find the optimal solution or analyze dynamical behavior of the system. Scanning gives the researcher a clear idea about a response surface and the global optimum. However practical application of scanning is limited up to 3-4 parameters due to dramatically increasing the number of numerical experiments:

$$N = m^k, \text{ where}$$

k is the dimension of the problem,

m is the number of levels for each parameter.

Let us consider basic features of the scanning how it realized in UM. The researcher can unite several models within on scanning project, see Figure 6.2. Set of numerical experiments is generated automatically. For each model the researcher describes default values of parameters, initial conditions, problem-specific parameters (road vehicles, railway vehicles, and flexible bodies), finish conditions, parameters of numerical method and list of variables that will be saved for each numerical experiment.

List of calculated variables can include all kinds of dynamical performances: coordinates, velocities, accelerations, components and modules of applied forces and moments etc.¹ Read <Sect. 4.3.3. List of variables> for details.

Finish conditions are formulated as follows:

<Variable1><logical operation1><Value1> OR

<Variable2><logical operation2><Value2> ..., where

<Variable i > is time or any UM variable.

¹ Practical experience shows that the list of variables can contain up to several decades and even hundreds different variables.

After fulfillment of all numerical experiments their results are available for analyzing, see Figure 6.4. It is possible to get plots for any variable from the list of variables as well as summary graphs, surfaces and tables.

Let us consider below usual work flow.

- The researcher adds all necessary models to the project and set all parameters for them, see Figure 6.2.
- A list of numerical experiments is generated automatically.
- The researcher runs the scanning project and all numerical experiments are finished automatically, possibly with the help of **UM Cluster**, see Figure 6.3.
- When the project is finished simulation results are available for analysis, see Figure 6.4.

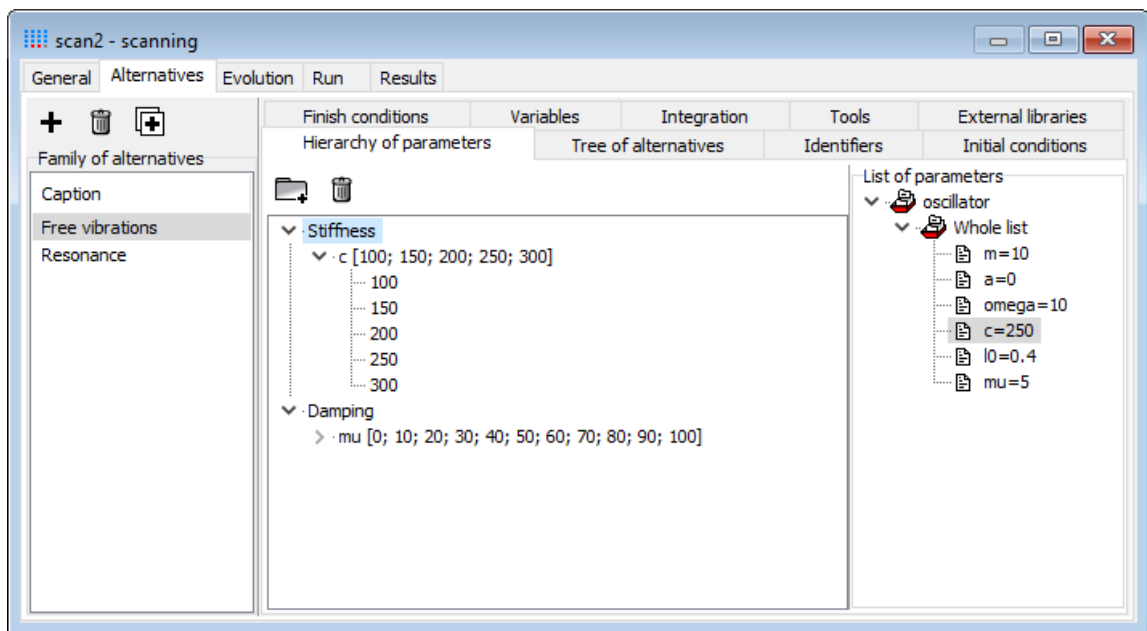


Figure 6.2. Scanning: hierarchy of parameters

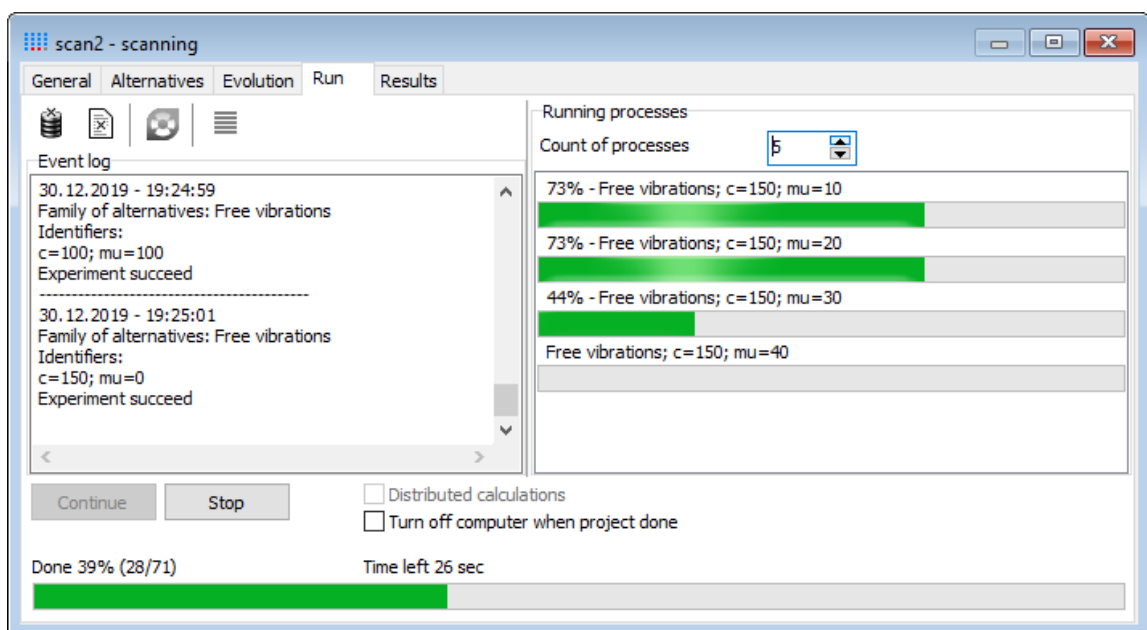


Figure 6.3. Running the scanning project

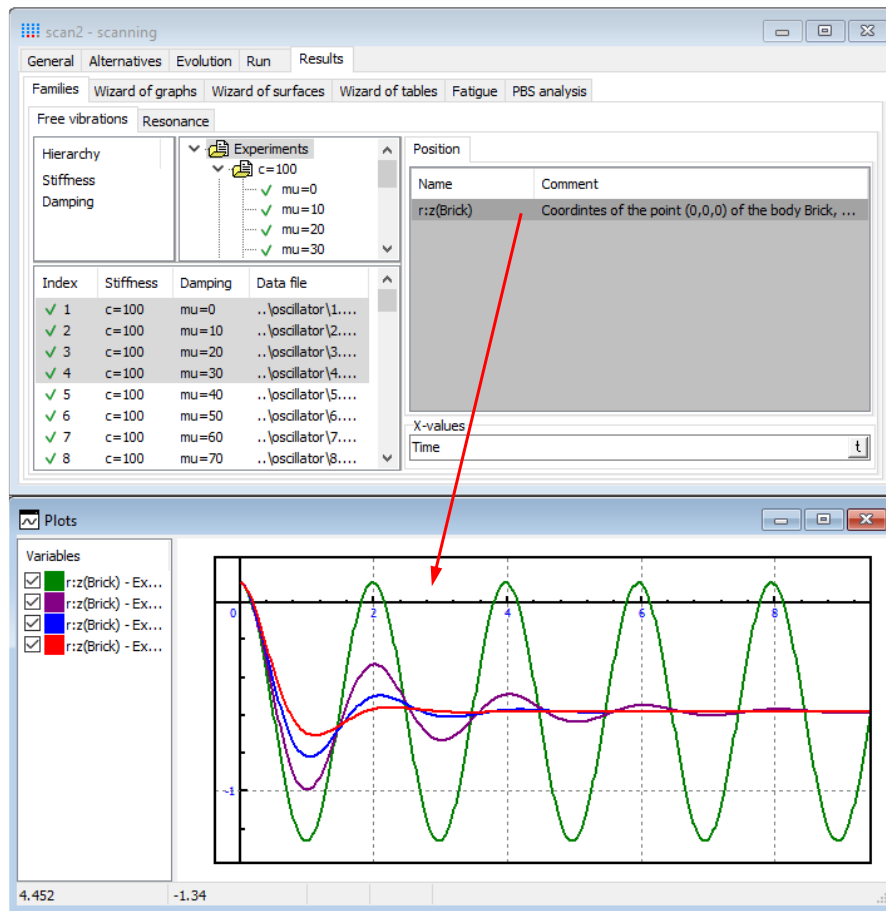


Figure 6.4. Scanning: processing results

6.3. Remarks

Project structure

The root directory of the scanning project includes subdirectories with models that are considered in this project. Once a model is added to the scanning project its source files are copied to the project directory as a subdirectory. Then all numerical experiments are fulfilled for this copy. All changes in the original model are ignored.

Portability

To copy/move the project it is necessary to copy/move its root directory. Such copying does not break the integrity of the project, you will be able to start/continue numerical experiments and analyze results.

Save as

Carrying out applied researches it is often necessary to fulfill the same scanning project with some small differences. The simplest way to do that is to save the project to another directory, modify the project and finally run it. There is the **Include simulation results** check box in the

dialog window, see Figure 6.5. Turn it on to save the scanning along with the preliminarily calculated simulation results. In such a case you the new and source projects will be totally same.

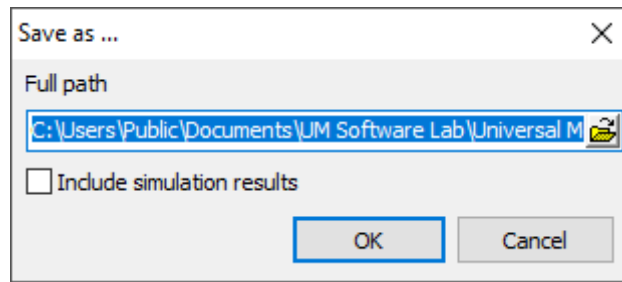


Figure 6.5. Save as dialog

Data files

After fulfillment every numerical experiment several data files are saved. Time history for every variable from the *list of variables* is saved, see Sect. 6.5.6. "Variables", p. 6-13. The more variables in the *list of variables* and the more simulation time the more size of data files. Practical experience shows that data files can reach *Gigabytes*. So if you have no enough free disk space you have to find compromise between the number of variables in the *list of variables*, simulation time and size of data files of the scanning project.

Deleting data files

To delete all data files you can click **Remove simulation results** button on the **General** or **Run** tabs. You also can delete data files for some numerical experiments to recalculate them. Select these numerical experiments in the list of experiments (see Figure 6.16) on the **Results** tab and select **Clear results** from a context menu, see Figure 6.6.

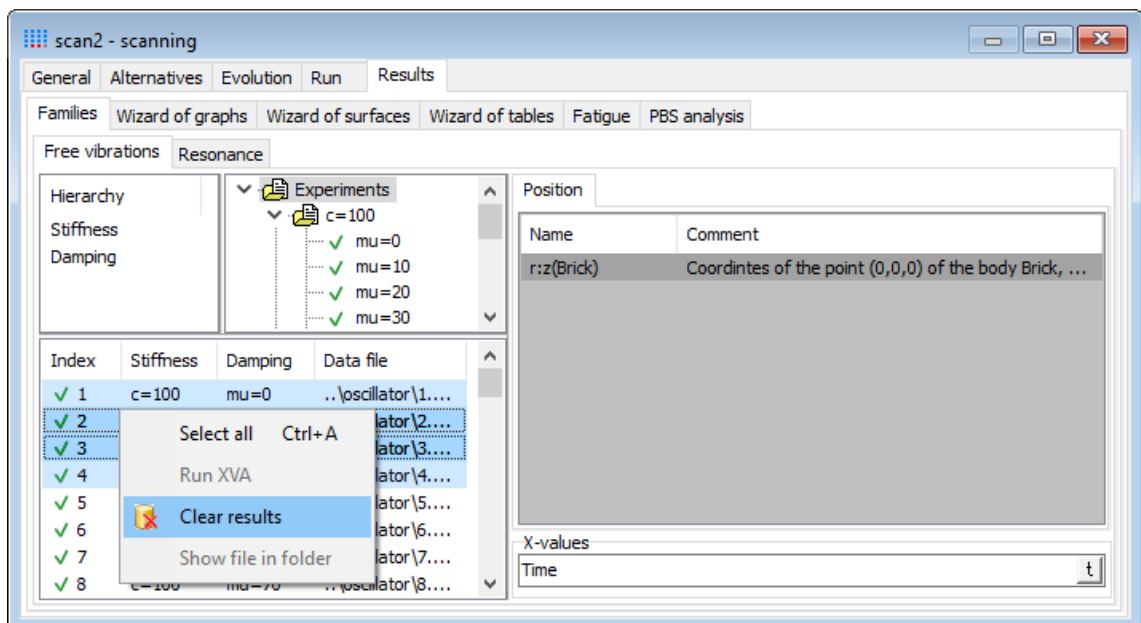


Figure 6.6. Deleting simulation results for some experiments

Project modification

You can modify the project at any stage of its fulfillment. For example, after fulfillment the project you can add a new model to a project. In this case to finish the project it is necessary to fulfill numerical experiments for the new model only.

You can also add some new levels for parameters for any model (family of alternatives). All already calculated experiments will keep their results. It gives a possibility to add new points in design space and thus specify dynamical behavior of the models step by step if necessary.

Also please note that all numerical experiments for every family are fulfilled with the same initial conditions, identifiers, parameters of numerical method, railway, road and other parameters. If any changes in any family settings are found the program shows dialog and asks the user saves these changes with or without clearing data files. Normally you are recommended to clear data files and fulfill all numerical experiments again.

6.4. Describing a new scanning project

Use the menu command **Scanning | New project...** to create a new scanning project. Every project should be placed in a separate directory. Therefore it is necessary to point out the directory when you create new scanning project, see Figure 6.7.

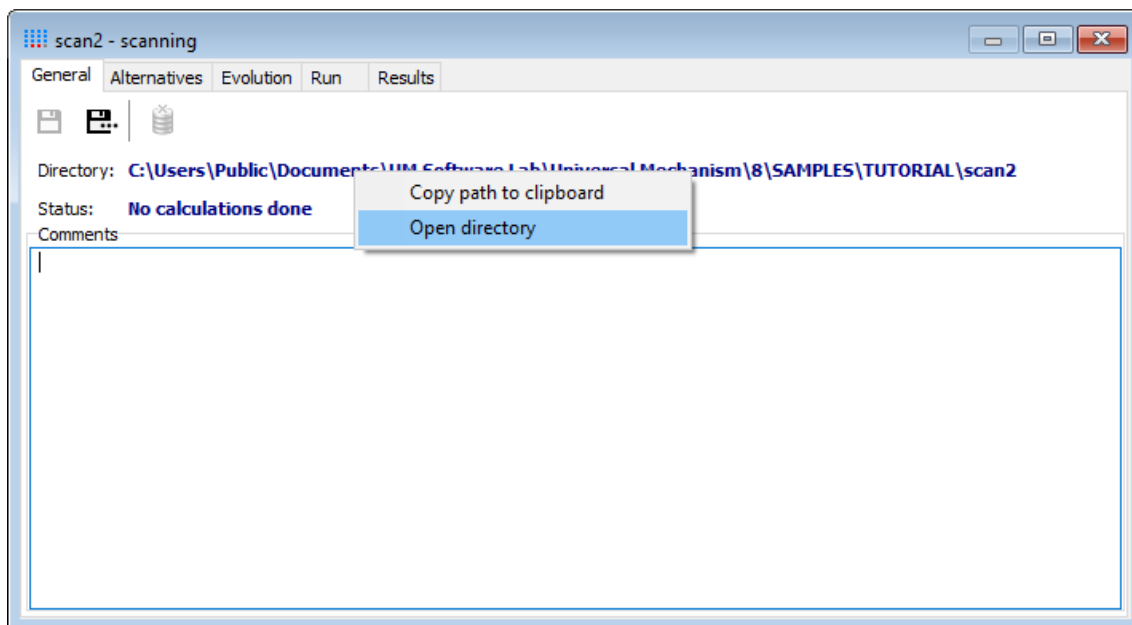


Figure 6.7. New scanning projects

6.5. Alternatives

A tab for description design parameters is shown in Figure 6.2. **Family of alternatives** is a group of alternatives generated by one model. Use **Add/Delete/Duplicate family** buttons or context menu (see Figure 6.8, Figure 6.9) to set up the project. It is necessary to describe hierarchy of parameters for each family. Hierarchy of parameters can be compare to nested loops. It means that for each value of upper level all values of lower level will be tabulated. Within a level, the parameters are changed jointly; number of iterations is determined by number of values of the first parameter at the level. If the number of iterations in the first parameter is less than ones of other parameters then final extra values are ignored, else the values of other parameters are taken over again.

Possibly it might be more suitable not to add new *families* and set all their parameters but just duplicate families and change their settings.

Setting considered in Sect. 6.5.1-6.5.7 are valid for active (current) family only. You should go through these steps for every family that you introduced in the project.

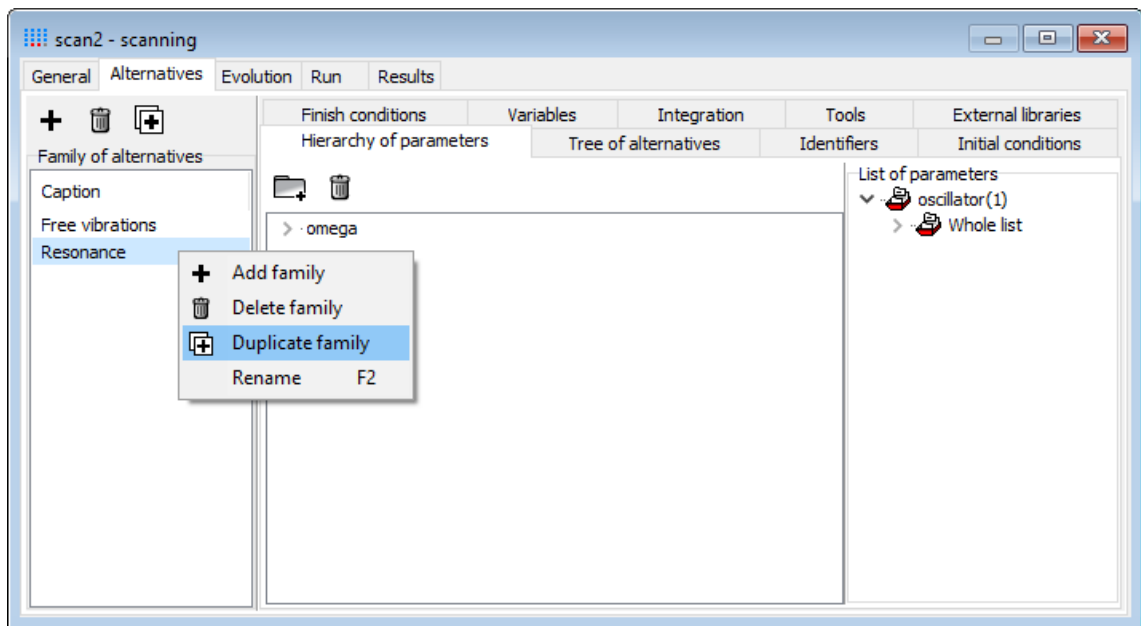


Figure 6.8. Family of alternatives: context menu

6.5.1. Hierarchy of parameters

You can use tool bar or context menu to add/remove levels of hierarchy or model parameters, see Figure 6.9. Double click onto any parameter from the **List of parameters** adds that parameter to current level of hierarchy. For example, the hierarchy in Figure 6.9. consists of two levels: **Stiffness** and **Damping**. **Stiffness** level consists of one parameter **c** having values [100, 150, 200, 250, 300]. **Damping** level consists of one parameter **mu** with values [0, 10, 20, 30..100].

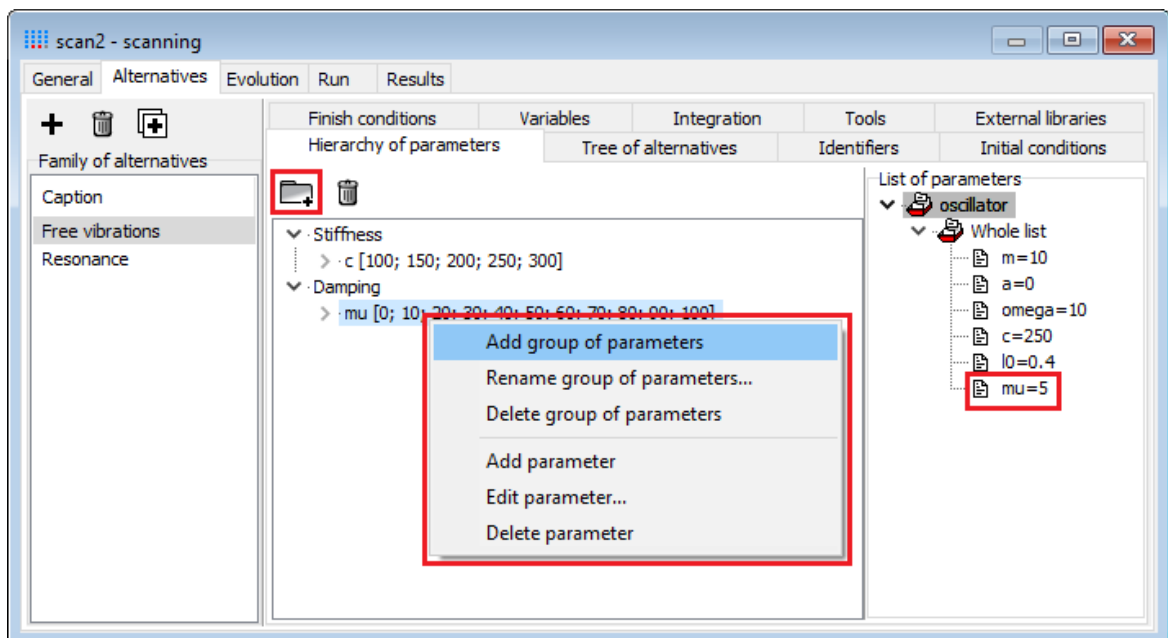


Figure 6.9. Hierarchy of parameters

6.5.2. Tree of alternatives

After description of hierarchy of parameters the full list (tree) of alternatives is generated automatically (see Figure 6.10). Tree of alternatives is on the top and list of alternatives is on the bottom.

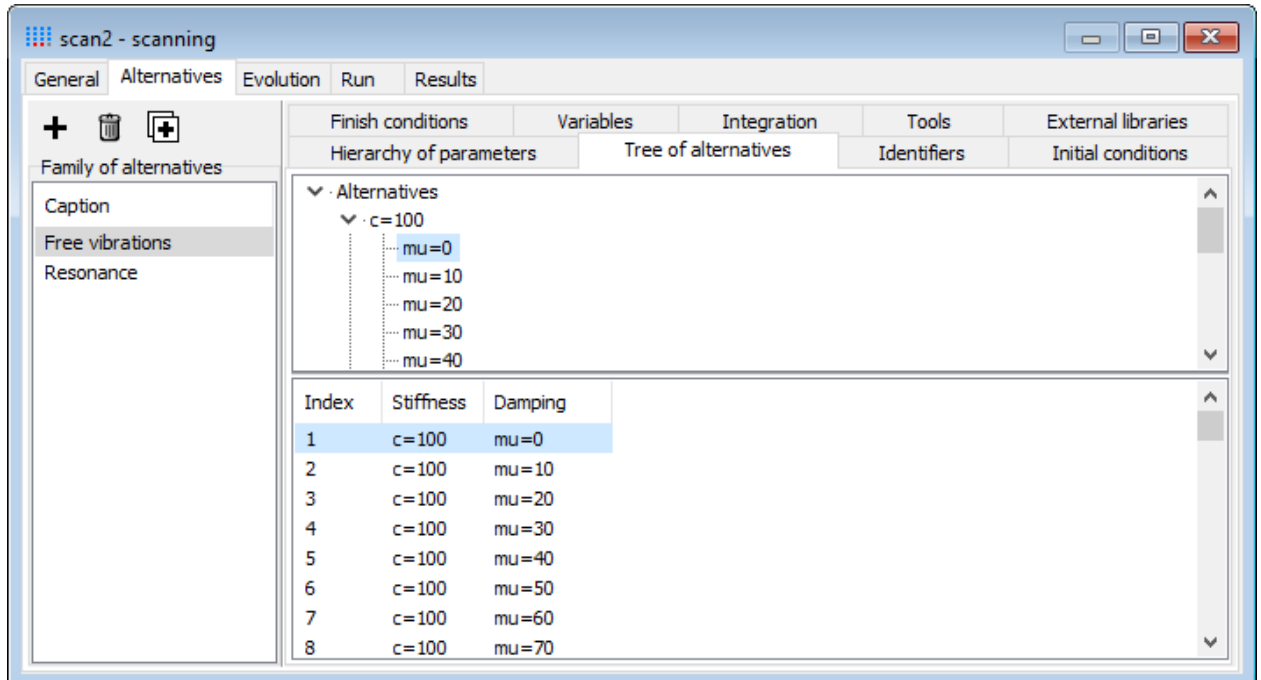


Figure 6.10. Tree of alternatives

6.5.3. Identifiers


Here you can find all of the system identifiers (see. Sect. 4.4.2.4). These values of identifiers will be used as default values for numerical experiments. The values are loaded before each numerical experiment. Of course, if an identifier changes as a design parameter then such an identifier will be redefined with the correspondent value.



6.5.4. Initial conditions


Here you can describe initial conditions each numerical experiment starts with (see Sect. 4.4.2.5).

6.5.5. Finish conditions

Here you can describe finish conditions for each numerical experiment in the current family, see Figure 6.11, Figure 6.12. Finish conditions are formulated in the following way: “Interrupt a numerical experiment if finish conditions are satisfied”. For example, the default finish conditions in Figure 6.11 means “Interrupt a numerical experiment if simulation time is more than 10 seconds”. Simulation time in this sense is the model time, not the real time of the user.

You can use time and any other variables as criteria for finish conditions. Create the necessary variable in the **Wizard of variables** (see Sect. 4.3.2. Wizard of variables) and drag it to the correspondent field, see Figure 6.12. Use  button to set time as a criterion again.

Buttons  /  are used to brace two conditions in brackets to change the priority of calculation. Example, that is given in Figure 6.12, means *Interrupt any numerical experiment, if (Time > 1.27 AND a:z(Brick) > 1) OR v:z(Brick) < 2.*

The first  button braces the first and the second finish conditions; the second button braces the second and the third finish conditions. It has no sense to turn on two buttons simultaneously – it makes no difference in calculation of finish conditions.

Please note that the logical operator *AND* has higher priority than the *OR* operator.

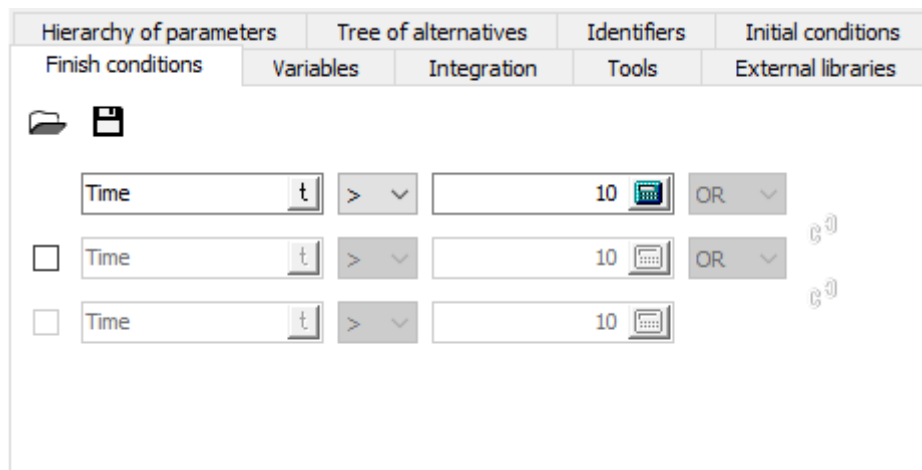


Figure 6.11. Default finish conditions

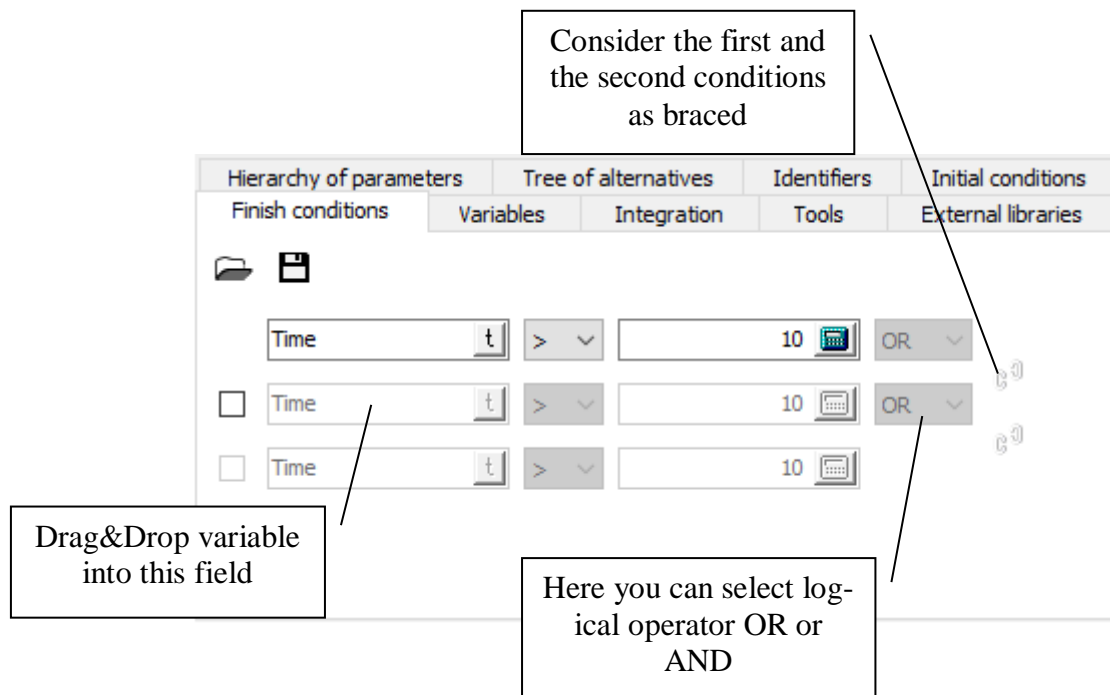


Figure 6.12. User-defined finish conditions

6.5.6. Variables

Here you should form a *list of variables* (see Sect. 4.3.3), which will be stored for every numerical experiment. Variables from this list will be available as results of *scanning*.

6.5.7. Integrator

Here you should choose integration method and set its parameters. This setting will be used for numerical simulation (see Sect. 4.4.2.1).

6.6. Running

When you activate the **Run** tab (see Figure 6.13), checking the description of scanning project is performed. You can see its results in the **Event log** field. If some errors are found, you should fix them and activate **Run** tab again.

When scanning project starts, the following information for each numerical experiment is available: time information, values of identifiers of hierarchy of parameters, summary information. A progress bar shows the ratio between number of done experiments and total number of experiments. Use the **Stop** button to interrupt execution. If any software or hardware breakdown appears, the results of the scanning project are not lost and execution will go on from the last unfulfilled experiment.

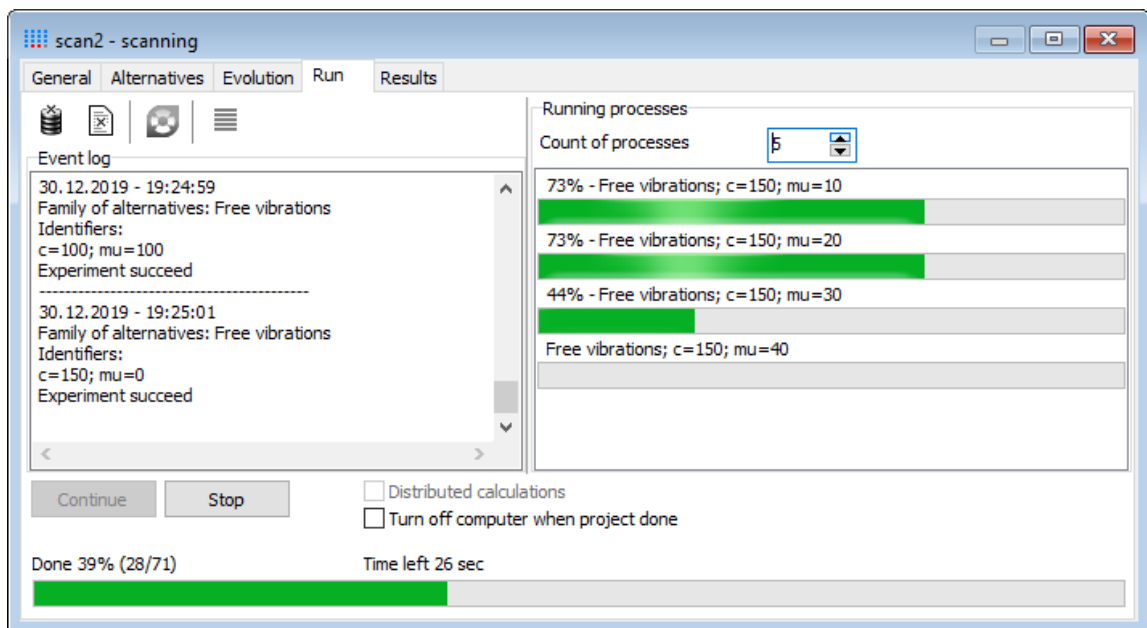


Figure 6.13. Running the project

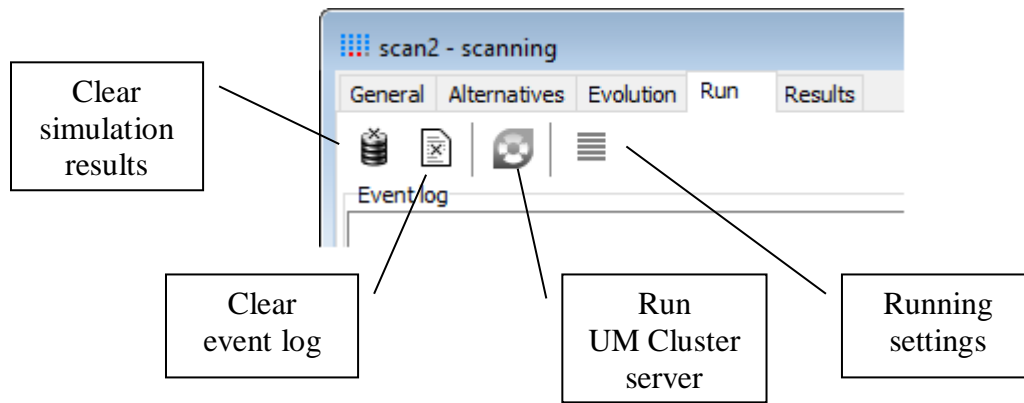


Figure 6.14. Toolbar on the Running tab sheet

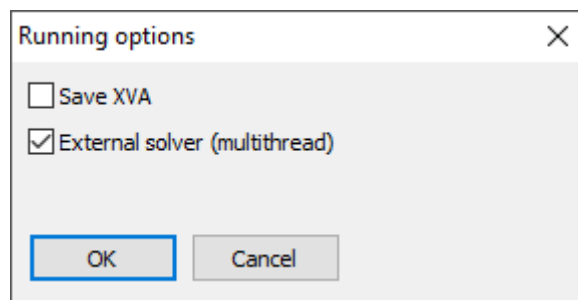


Figure 6.15. Running settings dialog

6.7. Results

If at least one numerical experiment is done then its results are available in the **Results** tab (see Figure 6.16). For each family of alternatives, there is the tab of the same name. There is a list of calculated variables on the right. On the left there is the list of numerical experiments. Fulfilled experiments are marked with the green sign, and unfulfilled ones are marked with the red one.

Select necessary experiments (use the **Shift** and the **Ctrl** keys in a standard way) from the list of experiments, then select necessary variables from the list and perform drag them to a graphical window. Variables in the graphical window have a correspondent comment, see Figure 6.16.

The tree of experiments corresponds to the list of experiments. Selection of a branch in the tree leads to selection the corresponding items in the list. Use the context menu of the hierarchy to change position of its levels and, as a result, fast selection of necessary experiments.

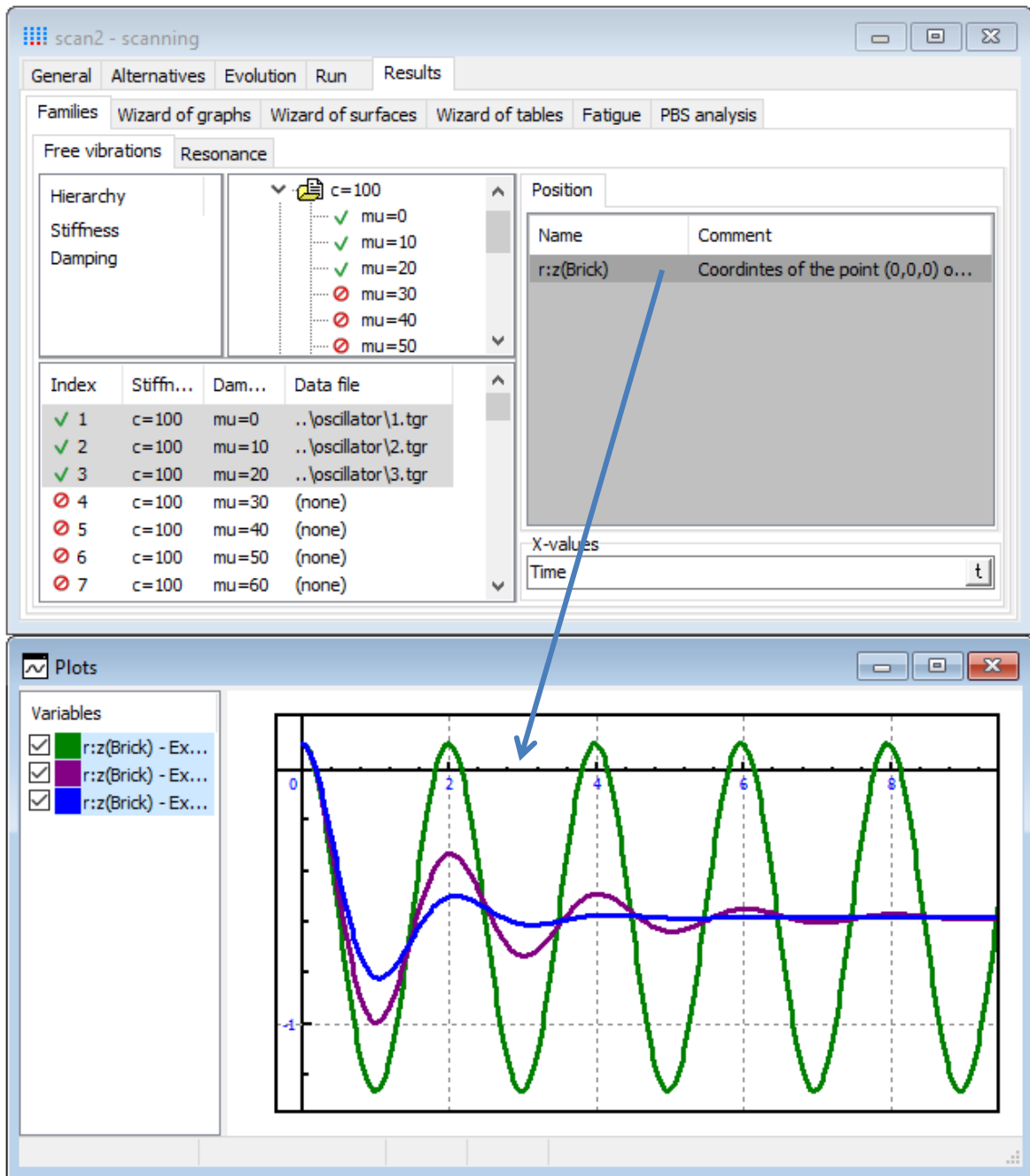



Figure 6.16. Processing results

6.7.1. Wizard of graphs

The **Wizard of graphs** (see Figure 6.17) is intended for forming dependence between a functional of any calculated variable on any parameter, when other parameters are fixed. Comments in the right bottom corner of the window will help you.

To add a summary graph you should go through the following steps.

- Choose a family, a variable to be analyzed, functional and parameter for computing dependence, see Figure 6.17.

- Optionally you can use limit for abscissa that can be used for excluding transient processes, as well as scale factors/units and interval for abscissa.
- Click the  button to plot the summary graph.
- To add new plot change the **Other parameters** if necessary and double click on the same or new variable in the **Criteria and variables** tree.

Note. **Other parameters** list is enabled if only scanning project has more than one level.

Let us consider an example, see Figure 6.17. Here we can see the root mean square of the vertical position of the 1 d.o.f. oscillation system in dependence on *omega* parameter. In this case of forced oscillation *omega* means the frequency of the driving force. The resonance case is clearly shown.

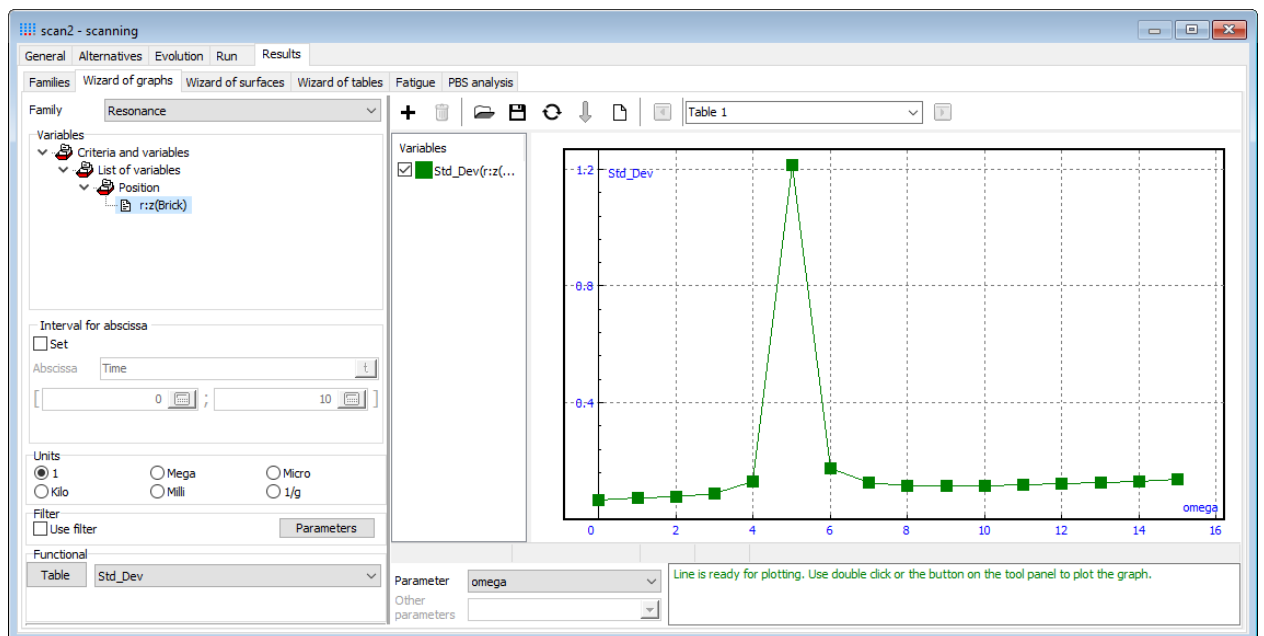


Figure 6.17. Wizard of graphs

Note. Choosing a new family of alternatives or a new parameter clears the table/graphs. Changing variables in the **Criteria and variables** tree keeps the table contents and can be used to obtain a group of dependences.

You can determine settings for **Abscissa limit**, **Units** and **Filter** during describing the scanning project in the **Variables** tab. To show these processing options use the button highlighted in Figure 6.18. In the presence of such processing options they will be used automatically.

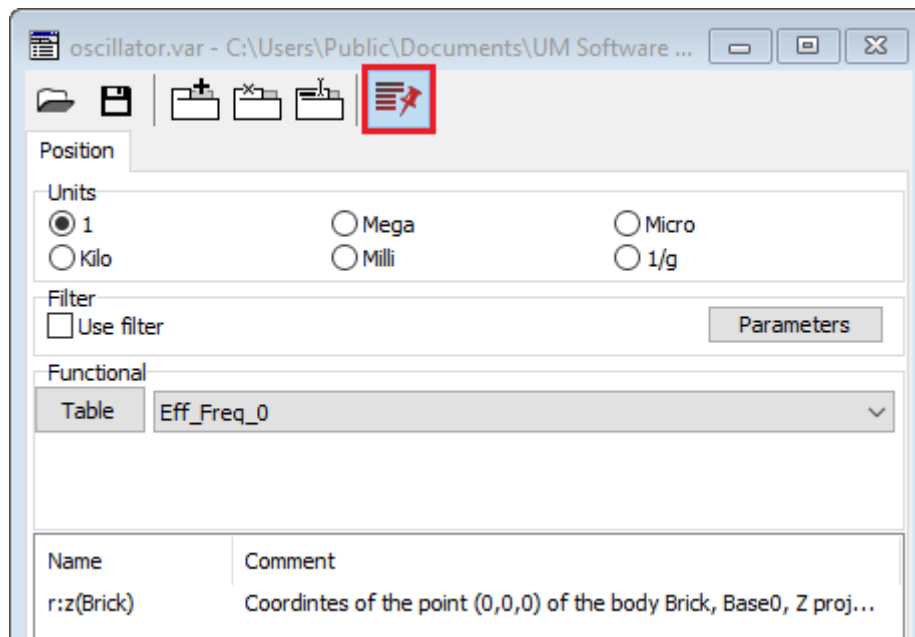


Figure 6.18. Settings of the list of variables

6.7.2. Wizard of surfaces

Wizard of surfaces is intended for creating the response surface as functional of any calculated variable in dependence on two any design parameters keeping other parameters constant. Working with **Wizard of surfaces** make sense if scanning has at least two design parameters. **Wizard of surfaces** is quite similar to **Wizard of graphs**. An example of using the **Wizard of surfaces** is given in Figure 6.19. Corresponding surface in *Microsoft Excel* is given in Figure 6.20.

Working with the **Wizard of surfaces** use the following work flow.

- Select the family, calculated variable or criterion and necessary functional, see Figure 6.19.
- Then choose two parameters for the surface and fix values of **other parameters** if any.
- Set **Abscissa limit**, **Units** and **Filter** parameters if necessary.
- You can export prepared surface to text file or clipboard as text table and to the *Microsoft Excel* as a diagram.

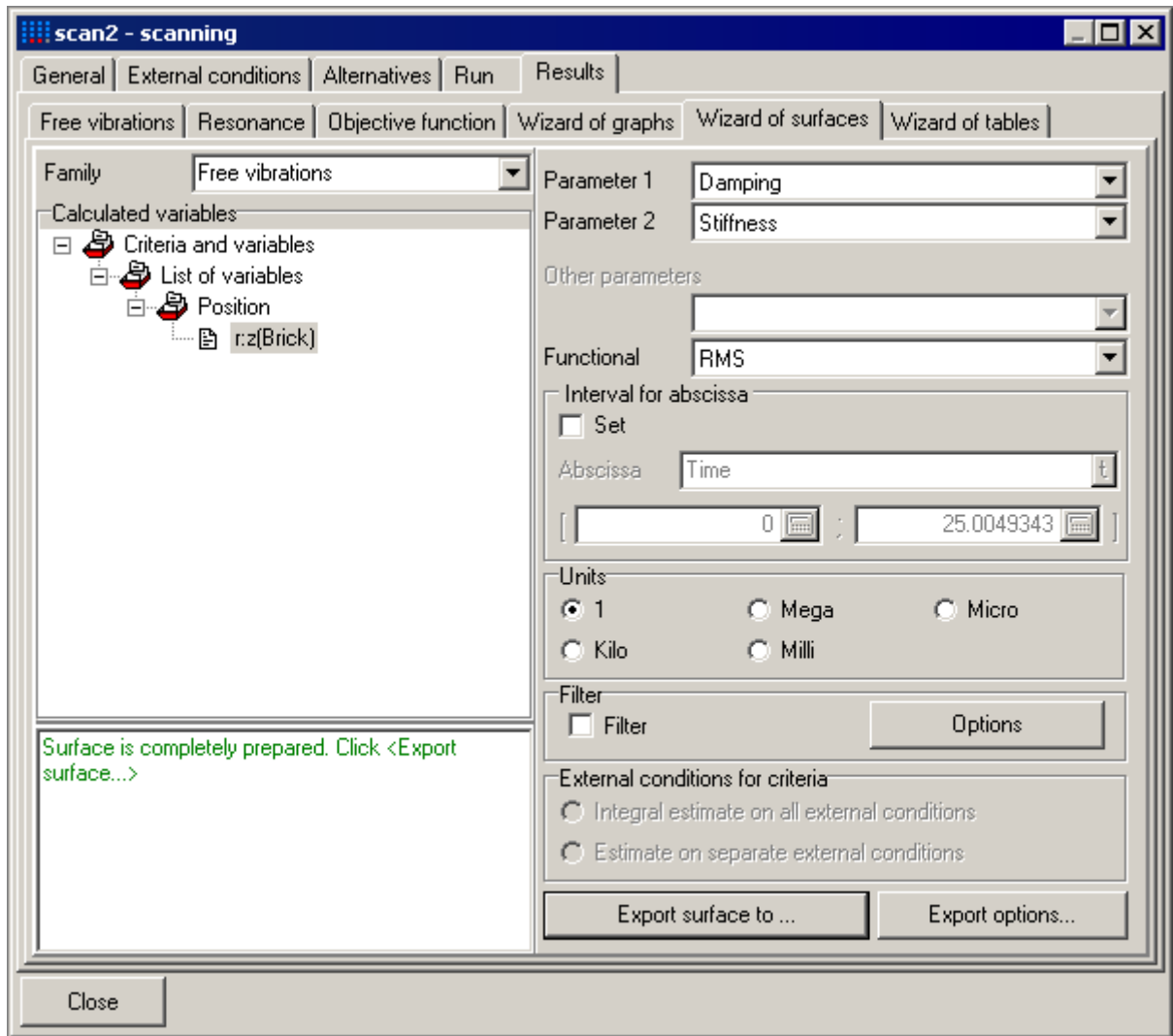


Figure 6.19. Wizard of surfaces

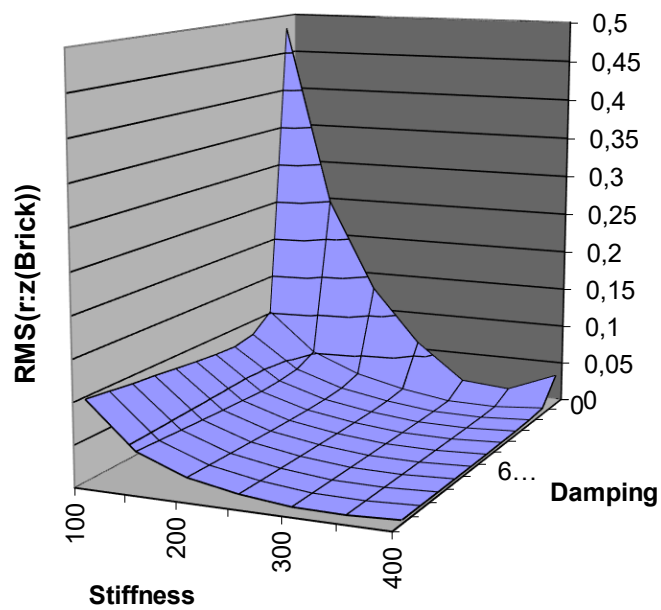


Figure 6.20. Exported surface